Runge-Kutta Methods

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Second Order Runge-Kutta Method

 $\frac{dy}{dx} = f(x, y)$ with the initial condition: $y(x_1) = y_1$

The general form of second-order Runge-Kutta methods is:

$$y_{i+1} = y_i + (c_1 K_1 + c_2 K_2)h$$

Con:

$$K_{1} = f(x_{i}, y_{i})$$
$$K_{2} = f(x_{i} + a_{2}h, y_{i} + b_{21}K_{1}h)$$

where c_1 , c_2 , a_2 , and b_{21} are constants. The values of these constants vary with the specific second-order method.

Modified Euler method in the form of a secondorder Runge-Kutta method

For the modified Euler method, the constants are:

$$c_1 = \frac{1}{2}, \quad c_2 = \frac{1}{2}, \quad a_2 = 1, \text{ and } b_{21} = 1$$

Substituting these constants yields:

$$y_{i+1} = y_i + \frac{1}{2}(K_1 + K_2)h$$

$$K_1 = f(x_i, y_i)$$

$$K_2 = f(x_i + h, y_i + K_1 h)$$

Midpoint method in the form of a second-order Runge-Kutta method

For the midpoint method, the constants are:

$$c_1 = 0$$
, $c_2 = 1$, $a_2 = \frac{1}{2}$, and $b_{21} = \frac{1}{2}$

Substituting these constants yields:

$$y_{i+1} = y_i + K_2 h$$

$$K_{1} = f(x_{i}, y_{i})$$
$$K_{2} = f\left(x_{i} + \frac{1}{2}h, y_{i} + \frac{1}{2}K_{1}h\right)$$

Heun's method

In Heun's method the constants are:

$$c_1 = \frac{1}{4}$$
, $c_2 = \frac{3}{4}$, $a_2 = \frac{2}{3}$, and $b_{21} = \frac{2}{3}$

Substituting these constants yields:

$$y_{i+1} = y_i + \left(\frac{1}{4}K_1 + \frac{3}{4}K_2\right)h$$

$$K_{1} = f(x_{i}, y_{i})$$
$$K_{2} = f\left(x_{i} + \frac{2}{3}h, y_{i} + \frac{2}{3}K_{1}h\right)$$

Example 1

Second Order Runge-Kutta Method in form of modified Euler

Problem:

$$\frac{dy}{dx} = 1 + y^{2} + x^{3}, \quad y(1) = -4$$

$$\int \mathbf{h} = 0.01$$

$$f(x, y) = 1 + y^{2} + x^{3}$$

$$x_{0} = 1, \quad y_{0} = -4$$

$$\begin{bmatrix} y_{i+1} = y_{i} + \frac{1}{2}(K_{1} + K_{2})h \\ K_{1} = f(x_{i}, y_{i}) \\ K_{2} = f(x_{i} + h, y_{i} + K_{1}h) \end{bmatrix}$$
Step 1:

$$K_{1} = f(x_{0}, y_{0}) = (1 + y_{0}^{2} + x_{0}^{3}) = 18.0$$

$$K_{2} = f(x_{0} + h, y_{0} + K_{1}h) = (1 + (y_{0} + 0.18)^{2} + (x_{0} + .01)^{3}) = 16.92$$

$$y_{1} = y_{0} + \frac{h}{2}(K_{1} + K_{2}) = -4 + \frac{0.01}{2}(18 + 16.92) = -3.8254$$

Example 1

Second Order Runge-Kutta Method: Modified Euler

Problem:

$$\frac{dy}{dx} = 1 + y^{2} + x^{3}, \quad y(1) = -4$$
Use RK2 to find $y(1.01), y(1.02)$

$$f(x, y) = 1 + y^{2} + x^{3}$$
 $x_{1} = 1.01, \quad y_{1} = -3.8254$
Step 2:
 $K_{1} = f(x_{1}, y_{1}) = (1 + y_{1}^{2} + x_{1}^{3}) = 16.66$
 $K_{2} = f(x_{1} + h, y_{1} + K_{1}h) = (1 + (y_{1} + 0.1666)^{2} + (x_{1} + .01)^{3}) = 15.45$
 $y_{2} = y_{1} + \frac{h}{2}(K_{1} + K_{2}) = -3.8254 + \frac{0.01}{2}(16.66 + 15.45) = -3.6648$

Example 1

Summary of the solution

Problem:

$$\frac{dy}{dx} = 1 + y^2 + x^3, \qquad y(1) = -4$$

Use RK2 to find y(1.01), y(1.02)

Summary of the solution

| i | X_{i} | \mathcal{Y}_i |
|---|---------|-----------------|
| 0 | 1.00 | -4.0000 |
| 1 | 1.01 | -3.8254 |
| 2 | 1.02 | -3.6648 |

Numerically Solving ODE in Matlab

Problem:

$$\frac{dy}{dx} = 1 + y^2 + x^3, \qquad y(1) = -4, \text{ over the interval}[1,2].$$

Using Euler modified with h=0.01, 0.02 y 0.5

$$y_{i+1} = y_i + \frac{1}{2}(K_1 + K_2)h \qquad K_1 = f(x_i, y_i) \\ K_2 = f(x_i + h, y_i + K_1h)$$

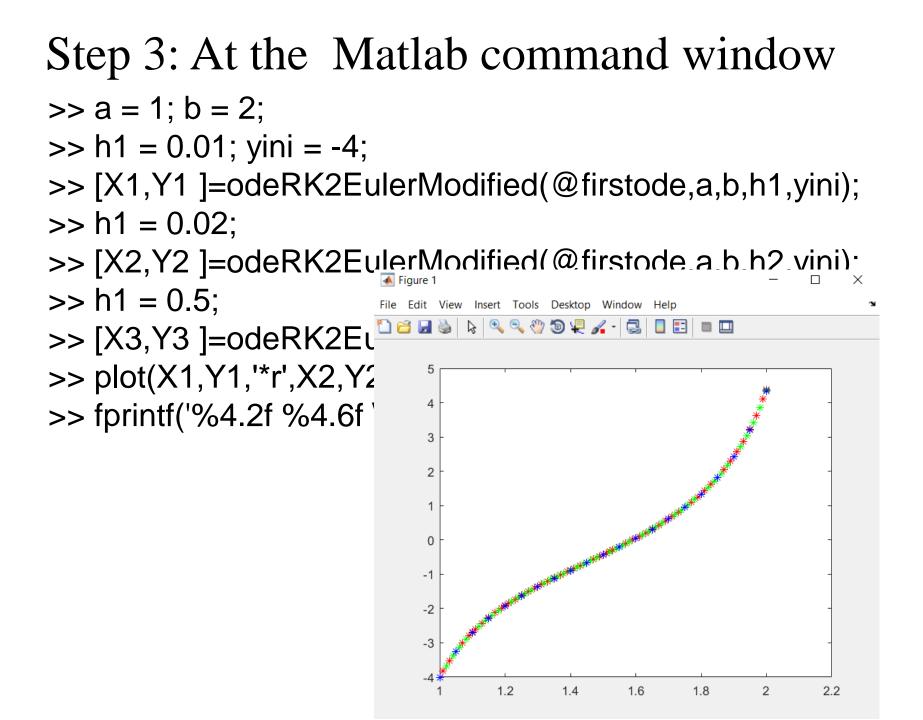
• Step 1: Create a M-file for dy/dx as firstode.m

function yprime=firstode(x,y);
yprime=1+y^2+x^3;

Step 2: Create a M-file to implement Euler modified. The Matlab program must return two column vectors, the first with values of x and the second with value of y.

```
[ function [ x,y ]=odeRK2EulerModified(ODE,a,b,h,yini)
🗄 % Variables de entrada:
 % ODE: Nombre para la función que calcula dy/dx.
 % a: Primer valor del intervalo de solucion x.
 % b: Ultimo valor del intervalo de solucion x.
 % h: Tamaño de paso.
 % vini: valor inicial.
 % De variables de salida:
 % x: Un vector con las coordenadas x de la solución.
 % y: Un vector con las coordenadas y de la solución.
 x(1) = a; y(1) = yini;
 n = (b-a)/h;
\Box for i = 1:n
    x(i+1) = x(i) + h;
     Kl = ODE(x(i), y(i));
     xh = x(i) + h;
     yKl = y(i) + Kl*h;
     K2 = ODE(xh, yKl);
     y (i + 1) = y (i) + (K1+K)*h*0.5;
 end
```

-end



Runge-Kutta Methods

Third Order Runge Kutta (RK3) $K_1 = f(x_i, y_i)$ $K_2 = f(x_i + \frac{1}{2}h, y_i + \frac{1}{2}K_1h)$ $K_3 = f(x_i + \frac{1}{2}h, y_i - K_1h + 2K_2h)$ $y(x+h) = y(x) + \frac{1}{6} \left(K_1 + 4K_2 + K_3 \right)$

Problem

Consider the following first-order ODE:

$$\frac{dy}{dt} = \frac{y}{t} - 0.5t^2$$
 from $t = 2$ to $t = 5$ with $y(2) = 4$

(a) Solve with the Heun's method using h = 0.5, 1. (b) Solve with the classical third-order Runge-Kutta method using h = 1.

The analytical solution of the ODE is:

$$y = -\frac{t^3}{4} + 3t$$

In each part, calculate the error between the true solution and the numerical solution at the points where the numerical solution is determined.

Classical Fourth-Order Runge-Kutta Method

The most popular RK methods are fourth-order, and the most commonly used form is:

$$y_{i+1} = y_i + \frac{1}{6} (k_1 + 2k_2 + 2k_3 + k_4)h$$

where:

$$k_{1} = f(t_{i}, y_{i})$$

$$k_{2} = f\left(t_{i} + \frac{1}{2}h, y_{i} + \frac{1}{2}k_{1}h\right)$$

$$k_{3} = f\left(t_{i} + \frac{1}{2}h, y_{i} + \frac{1}{2}k_{2}h\right)$$

$$k_{4} = f\left(t_{i} + h, y_{i} + k_{3}h\right)$$

Exercise

Solving by hand a first-order ODE using the fourth-order Runge-Kutta method.

 $\frac{dy}{dx} = -1.2y + 7e^{-0.3x}$ from x = 0 to x = 2.5 with the initial condition y = 3 at x = 0.

Using h = 0.5.

Solution:

The first point of the solution is (0,3), which is the point where the initial condition is given. The values of x and y at the first point are $x_1=0$ and $y_1=3$. The rest of the solution is done in steps. In each step the next value of the independent variable is calculated by:

$$x_{i+1} = x_i + h = x_i + 0.5$$

The value of the dependent variable Y_{i+1} is calculated by first evaluating K1, K2, K3 and K4 using:

$$K_{1} = f(x_{i}, y_{i})$$

$$K_{2} = f\left(x_{i} + \frac{1}{2}h, y_{i} + \frac{1}{2}K_{1}h\right)$$

$$K_{3} = f\left(x_{i} + \frac{1}{2}h, y_{i} + \frac{1}{2}K_{2}h\right)$$

$$K_{4} = f(x_{i} + h, y_{i} + K_{3}h)$$

And then substituting the Ks:

$$y_{i+1} = y_i + \frac{1}{6}(K_1 + 2K_2 + 2K_3 + K_4)h$$

First step: In the first step i = 1

$$\begin{aligned} x_2 &= x_1 + 0.5 = 0 + 0.5 = 0.5 \\ K_1 &= -1.2y_1 + 7e^{-0.3x_1} = -1.2 \cdot 3 + 7e^{-0.3 \cdot 0} = 3.4 \\ x_1 + \frac{1}{2}h &= 0 + \frac{1}{2} \cdot 0.5 = 0.25 \quad y_1 + \frac{1}{2}K_1h = 3 + \frac{1}{2} \cdot 3.4 \cdot 0.5 = 3.85 \\ K_2 &= -1.2\left(y_1 + \frac{1}{2}K_1h\right) + 7e^{-0.3\left(x_1 + \frac{1}{2}h\right)} = -1.2 \cdot 3.85 + 7e^{-0.3 \cdot 0.25} = 1.874 \\ y_1 + \frac{1}{2}K_2h &= 3 + \frac{1}{2} \cdot 1.874 \cdot 0.5 = 3.469 \\ K_3 &= -1.2\left(y_1 + \frac{1}{2}K_2h\right) + 7e^{-0.3\left(x_1 + \frac{1}{2}h\right)} = -1.2 \cdot 3.469 + 7e^{-0.3 \cdot 0.25} = 2.331 \\ y_1 + K_3h &= 3 + 2.331 \cdot 0.5 = 4.166 \\ K_4 &= -1.2(y_1 + K_3h) + 7e^{-0.3(x_1 + h)} = -1.2 \cdot 4.166 + 7e^{-0.3 \cdot 0.5} = 1.026 \\ y_2 &= y_1 + \frac{1}{6}(K_1 + 2K_2 + 2K_3 + K_4)h = 3 + \frac{1}{6}(3.4 + 2 \cdot 1.874 + 2 \cdot 2.331 + 1.026) \cdot 0.5 = 4.069 \\ \text{At the end of the first step: } x_2 &= 0.5, y_2 = 4.069 \end{aligned}$$

Second step: In the second step i = 2

$$\begin{aligned} x_3 &= x_2 + 0.5 = 0.5 + 0.5 = 1.0 \\ K_1 &= -1.2y_2 + 7e^{-0.3x_2} = -1.2 \cdot 4.069 + 7e^{-0.3 \cdot 0.5} = 1.142 \\ x_2 + \frac{1}{2}h &= 0.5 + \frac{1}{2} \cdot 0.5 = 0.75 \quad y_2 + \frac{1}{2}K_1h = 4.069 + \frac{1}{2} \cdot 1.142 \cdot 0.5 = 4.355 \\ K_2 &= -1.2\left(y_2 + \frac{1}{2}K_1h\right) + 7e^{-0.3\left(x_2 + \frac{1}{2}h\right)} = -1.2 \cdot 4.355 + 7e^{-0.3 \cdot 0.75} = 0.3636 \\ y_2 + \frac{1}{2}K_2h &= 4.069 + \frac{1}{2} \cdot 0.3636 \cdot 0.5 = 4.16 \\ K_3 &= -1.2\left(y_2 + \frac{1}{2}K_2h\right) + 7e^{-0.3\left(x_2 + \frac{1}{2}h\right)} = -1.2 \cdot 4.16 + 7e^{-0.3 \cdot 0.75} = 0.5976 \\ y_2 + K_3h &= 4.069 + 0.5976 \cdot 0.5 = 4.368 \\ K_4 &= -1.2(y_2 + K_3h) + 7e^{-0.3(x_2 + h)} = -1.2 \cdot 4.368 + 7e^{-0.3 \cdot 1.0} = -0.0559 \\ y_3 &= y_2 + \frac{1}{6}(K_1 + 2K_2 + 2K_3 + K_4)h = 4.069 + \frac{1}{6}[1.142 + 2 \cdot 0.3636 + 2 \cdot 0.5976 + (-0.0559)] \cdot 0.5 = 4.32 \\ \text{At the end of the second step: } x_3 &= 1.0, y_3 &= 4.32 \end{aligned}$$

Third step: In the third step i = 3

$$\begin{aligned} x_4 &= x_3 + 0.5 = 1.0 + 0.5 = 1.5 \\ K_1 &= -1.2y_3 + 7e^{-0.3x_3} = -1.2 \cdot 4.32 + 7e^{-0.3 \cdot 1.0} = 0.001728 \\ x_3 + \frac{1}{2}h &= 1.0 + \frac{1}{2} \cdot 0.5 = 1.25 \qquad y_3 + \frac{1}{2}K_1h = 4.32 + \frac{1}{2} \cdot 0.001728 \cdot 0.5 = 4.320 \\ K_2 &= -1.2\left(y_3 + \frac{1}{2}K_1h\right) + 7e^{-0.3\left(x_3 + \frac{1}{2}h\right)} = -1.2 \cdot 4.32 + 7e^{-0.3 \cdot 1.25} = -0.373 \end{aligned}$$

$$y_{3} + \frac{1}{2}K_{2}h = 4.32 + \frac{1}{2} \cdot (-0.373) \cdot 0.5 = 4.227$$

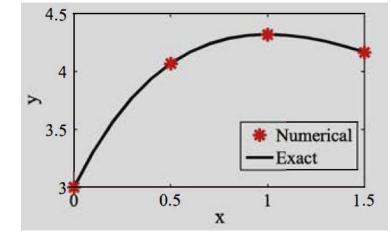
$$K_{3} = -1.2 \left(y_{3} + \frac{1}{2}K_{2}h \right) + 7e^{-0.3\left(x_{3} + \frac{1}{2}h\right)} = -1.2 \cdot 4.227 + 7e^{-0.3 \cdot 1.25} = -0.2614$$

$$y_{3} + K_{3}h = 4.32 + (-0.2614) \cdot 0.5 = 4.189$$

$$K_{4} = -1.2(y_{3} + K_{3}h) + 7e^{-0.3(x_{3} + h)} = -1.2 \cdot 4.189 + 7e^{-0.3 \cdot 1.5} = -0.5634$$

$$y_{4} = y_{3} + \frac{1}{6}(K_{1} + 2K_{2} + 2K_{3} + K_{4})h = 4.32 + \frac{1}{6}[0.001728 + 2 \cdot (-0.373) + 2 \cdot (-0.2614) + (-0.5634)] \cdot 0.5 = 4.167$$
At the end of the third step: $x_{4} = 1.5$, $y_{4} = 4.167$

| i | 1 | 2 | 3 | 4 |
|-------------------|-----|-------|------|-------|
| x_i | 0.0 | 0.5 | 1.0 | 1.5 |
| y_i (numerical) | 3.0 | 4.069 | 4.32 | 4.167 |



Problem

Write a user-defined MATLAB function that solves a first-order ODE using the classical fourth order Runge-Kutta method.

 $\frac{dy}{dx} = -1.2y + 7e^{-0.3x}$ from x = 0 to x = 2.5 with the initial condition y = 3 at x = 0.

Compare the results with the exact (analytical) solution: $y = \frac{70}{9}e^{-0.3x} - \frac{43}{9}e^{-1.2x}$.

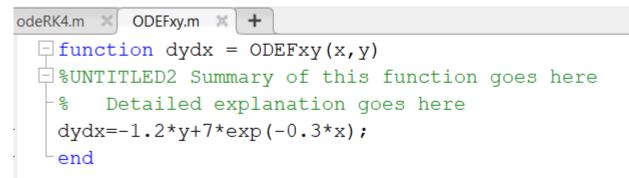
Using h=0.05.

Solution

To solve the problem, a user-defined MATLAB function called odeRK4, which solves a first-order initial value ODE, is written. The function is then used in a script file, which also generates a plot that shows a comparison between the numerical and the exact solutions. The ODE itself is written in a separate user-defined function that is used by the odeRK4 function.

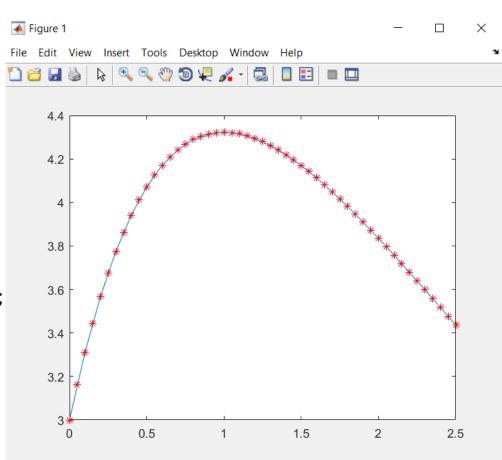
```
odeRK4.m 🗶 ODEFxy.m 🗶 🕂
   [ function [ x,y ]=odeRK4(ODE,a,b,h,yini)
   ⊡% Variables de entrada:
     % ODE: Nombre para la función que calcula dy/dx.
     % a: Primer valor del intervalo de solucion x.
     % b: Ultimo valor del intervalo de solucion x.
     % h: Tamaño de paso.
     % yini: valor inicial.
     % De variables de salida:
     % x: Un vector con las coordenadas x de la solución.
    -% y: Un vector con las coordenadas y de la solución.
    x(1) = a; y(1) = yini;
    n = (b-a)/h
   \bigcirc for i = 1:n
         x(i+1) = x(i) + h;
-
-
-
-
-
         Kl = ODE(x(i), y(i));
         xhalf = x(i) + h/2;
         yKl = y(i) + Kl*h/2;
        K2 = ODE(xhalf, yKl);
         yK2 = y(i) + K2*h/2;
         K3 = ODE(xhalf, yK2);
         yK3 = y(i) + K3*h;
         K4 = ODE(x(i + 1), yK3);
         y (i + 1) = y (i) + (Kl + 2*K2 + 2*K3 + K4) *h/6;
     end
     end
```

Funcion ODEFxy



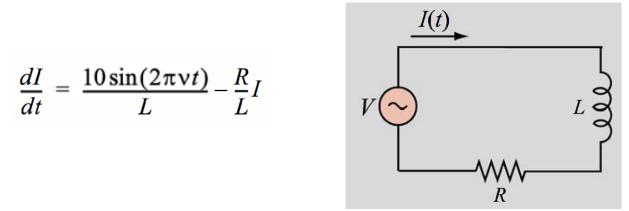
At the Matlab command window

```
>> a=0; b=2.5;
>> h=0.05; yini=3;
>> [x,y]=odeRK4(@ODEFxy,a,b,h,yini);
Solusion Exacta
>> xp=a:0.1:b;
>>yp=70/9*exp(-0.3*xp)-43/9*exp(-1.2*xp);
>>plot(x,y, '*r',xp,yp)
```



Problem

An inductor L = 15 H and a resistor R = 1000 ohms are connected in series with an AC power source providing voltage of V = $10\sin(2\pi vt)$ Vots, where v=100 kHz, as shown in the figure. The current *I*(t) in the circuit is determined from the solution of the equation:



Solve the equation and plot the current as a function of time for $0 \le t \le 1 \ge 10^{-4}$ s with I(0) = 0. Using $h=10^{-9}$ s.